COMP9312_23T2





Outline

- Basic Concepts
- Triangle Counting
- General Subgraph Matching



Graph Homomorphism

Two graphs G and H are homomorphic, if there exists a function $f: V_G \rightarrow V_H$ between vertices of the graph such that if $\{a, b\}$ is an edge in G then $\{f(a), f(b)\}$ is an edge in H.



An idea case...



Graph Homomorphism (cont)

Some other cases ...







Try to find the mapping function

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Graph Isomorphism

Two graphs *G* and *H* are isomorphic, if there exists a **bijection** $f: V_G ->V_H$ between vertices of the graph such that if $\{a, b\}$ is an edge in *G* then $\{f(a), f(b)\}$ is an edge in *H*.





f(a) = 4		f(a) = 4
f(b) = 5		f(b) = 5
f(c) = 1	or	f(c) = 3
f(d) = 3		f(d) = 1
f(e) = 2		f(e) = 2



Given a query graph Q and a data graph G, compute (count/enumerate) all subgraphs of G that are isomorphic to Q.

All matching instances of f(1), f(2), f(3), f(4):



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```
<b,c,a,e> <c,b,a,e>
<a,c,b,d> <c,a,b,d>
<g,f,e,a> <f,g,e,a>
<e,g,f,h> <g,e,f,h>
```



The query graph is symmetric



Application

- Bioinformatics of protein-protein interaction networks
- Chemistry (similarity between chemical compounds)
- Node representation
- Malware detection
- System analysis



- Exact counting/enumeration
 - Specific patterns (triangle, k-clique, butterfly, ...)
 - General subgraphs
- Approximate counting (estimation)
 - Probability theory
 - Graph Neural Networks



Count all triangles in a graph.



Five triangles exist in this example.



Edge-iterator: Given an edge (u, v), any triangle that includes the edge must contain a third vertex w that has connections to both of u and v. Thus, we can obtain any triangles containing edge (u, v) based on the intersection of N(u) and N(v). For each edge, the edge-iterator returns the set of triangles associated with that edge, and when repeated on all edges, the set of all triangle solutions is made available.

Duplication: If we use the above method to calculate the triangles, then we will count a triangle repeatedly.

Latapy, M. (2008). Main-memory triangle computations for very large (sparse (power-law)) graphs. *Theoretical computer science*, *407*(1-3), 458-473.





Priority: The priority of vertices can be determined by the degree of each vertex. The smaller the degree; the smaller the priority. If the degrees of two vertices are the same, it can be determined by the alphabetical order or numerical order of the vertices.

Orientation technique (without duplication): Each undirected edge is mapped to a directed edge where the direction (i.e., orientation) is decided by the priority of its endpoints in the vertex-ordering (i.e., u->v if u has a higher priority than v). We refer to vertex u as a pivot vertex if u has two out-going edges. We can association a triangle in the undirected graph with only one pivot vertex to ensure one and only one instance of this triangle in the output, which significantly improves the performance.

Latapy, M. (2008). Main-memory triangle computations for very large (sparse (power-law)) graphs. Theoretical computer science, 407(1-3), 458-473.



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Compact Forward (CF) Algorithm: We denote the set of outgoing-neighbors of vertex u in G as $N^+(u)$, and the out-degree as $deg^+(u) = |N^+(u)|$. In line 1, undirected graph G is transformed into a directed graph G via the orientation technique. (Line 2 onward follows the edge-iterator framework.) In Line 3, triangles are enumerated by iterating through the outgoing neighborhoods rather than the full neighborhood. In Line 4, a merge-based intersection identifies the common out-going neighbors of u and v, denoted by T. A set of triangles (u, v, w) is then output for every vertex w \in T.



Algorithm 1: CF(G)

The adjacency list of each vertex is unsorted: The time complexity of CF algorithm is: $O(\sum_{(u,v)\in E} deg^+(u) * deg^+(v))$.

Proof: We need to check whether there are common neighbors in the adjacency list of u and v. For each neighbor of u, we need to check $deg^+(v)$ times in the adjacency list of v, u has $deg^+(u)$ neighbors, so the time complexity of finding common neighbor of two vertices (line 4 in the pseudo code) is $O(deg^+(u) * deg^+(v))$. Thus, the total time complexity of CF algorithm is: $O(\sum_{(u,v)\in E} deg^+(u) * deg^+(v))$.

Adjacency list of u:

For the sake of brevity, here we only give the out-neighbors of u and v and the degree of vertices other than u, v is higher than the degree of u, v.



If the adjacency list of each vertex is sorted, the merge-based intersection operation at Line 4 takes $O(deg^+(u) + deg^+(v))$. The time complexity of CF algorithm is: $O(\sum_{(u,v)\in E} deg^+(u) + deg^+(v))$.

Ordered adjacency list of u:





Suppose a hash table has been built for each vertex based on the out-going neighbors in the oriented graph. At Line 4 of Algorithm CF, we may choose the vertex with larger number of neighbors as the hash table for intersection operation with $O(\min(deg^+(u), deg^+(v)))$ look-up cost.

A hash table has been built for each vertex: The time complexity of CF algorithm is: $O(\sum_{(u,v)\in E} \min(deg^+(u), deg^+(v))) = O(\sum_{(u,v)\in E} \min(deg(u), deg(v))) = O(\alpha \cdot m) = O(m^{1.5}).$



https://en.wikipedia.org/wiki/Arboricity

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Adjacency list of u: N+(u)ABDEIAdjacency list of v: N+(v)BFI

Choosing the vertex with larger number of neighbors as the hash table for intersection operation.



Here is an example of u's hash table. We use division hashing to make this hash table. The value of the vertex is replaced by the corresponding number (A: 1, B: 2, D: 4, E: 5, I: 9) and the hash function used is X % 5.

Because the query time complexity of hash table is O(1), we only need to query $deg^+(v)$ times.

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Final result: there are two common neighbors B and I.

- Building a hash table for neighbors of each vertex takes too much space for big graphs.
- Utilize the degree order
- Scan the smaller set -> scan the out neighbor of v

A hash table is being built on the fly: The time complexity of CF algorithm is: $O(\sum_{(u,v)\in E'} deg^+(v)) = O(\sum_{(u,v)\in E'} deg(v)) = O(\sum_{(u,v)\in E} \min(deg(u), deg(v)))$ $= O(\alpha \cdot m) = O(m^{1.5}).$

E': the set of all directed edges

Coding practice~



General Subgraph Matching



Avoid redundancy for symmetric query graphs by enforcing f(1) < f(2)

All matching instances of *f(1), f(2), f(3), f(4)*: <a,c,b,d> <c,a,b,d> <b,c,a,e> <c,b,a,e> <f,g,e,a> <g,f,e,a> <e,g,f,h> <g,e,f,h>



- 1. Set up a matching order
- 2. Match following the order
- 3. Apply pruning rules





23



b

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Data graph

h

connectivity

Further Optimization

- Matching plan
 - order plan (vertex-based)
 - join plan (vertex-based)
- Efficient common neighbor computation



K-Clique Enumeration

A clique is a graph in which every pair of vertices are connected.

A k-clique is a clique with k vertices.

Can you design an algorithm to enumerate all k-cliques?





4-clique

